Autonics

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- ▲ symbol indicates caution due to special circumstances in which hazards may occur.
- **Warning** Failure to follow instructions may result in serious injury or death.
- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.) ailure to follow this instruction may result in personal injury, economic loss or fire.
 - 02. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
 - Failure to follow this instruction may result in explosion or fire. 03. Install on a device panel to use.
 - Failure to follow this instruction may result in fire. 04. Do not connect, repair, or inspect the unit while connected to a power source.
 - Failure to follow this instruction may result in fire. 05. Check 'Connections' before wiring.
 - Failure to follow this instruction may result in fire. **06. Do not disassemble or modify the unit.** Failure to follow this instruction may result in fire.

▲ Caution Failure to follow instructions may result in injury or product damage.

- 01. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage. 02. Do not short the load.
- Failure to follow this instruction may result in fire. 03. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists. Failure to follow this instruction may result in product damage.

Cautions during Use

Safety Considerations

- Follow instructions in 'Cautions during Use'.
- Otherwise, It may cause unexpected accidents. 5 VDC=, 12 VDC= power supply should be insulated and limited voltage / current or Class 2, SELV power supply device.
- · For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal. • Ground the shield wire to the F.G. terminal.
- When supplying power with SMPS, ground the F.G. terminal and connect the noise canceling capacitor between the 0 V and F.G. terminals. · Wire as short as possible and keep away from high voltage lines or power lines, to
- prevent inductive noise.
- For Line driver unit, use the twisted pair wire which is attached seal and use the receiver for RS-422A communication.
- · Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc. by line resistance or capacity between lines.
- This unit may be used in the following environments - Indoors (in the environment condition rated in 'Specifications')
- Altitude max. 2,000 m - Pollution degree 2
- Installation category II

Features

E20 Series

PRODUCT MANUAL

manual, other manuals and Autonics website.

• Ultra-compact (Ø 20 mm) housing and lightweight (35 g) design

improvement. Some models may be discontinued without notice.

For your safety, read and follow the considerations written in the instruction

The specifications, dimensions, etc. are subject to change without notice for product

- · Easy installation in tight or limited spaces
- Low shaft moment of inertia
- Various resolutions: 100, 200, 320, 360 pulses per revolution
- Various control output options
- Power supply: 5 VDC== ± 5%, 12 VDC== ± 5%

20 mm Diameter



Incremental Rotary Encoders

Cautions during Installation

- Install the unit correctly with the usage environment, location, and the designated specifications.
- Do not load overweight on the shaft.
- Do not put strong impact when insert a coupling into shaft. Failure to follow this instruction may result in product damage.
- When fixing the product or coupling with a wrench, tighten under 0.15 N m.
 If the coupling error (parallel misalignment, angular misalignment) between the shaft increases while installation, the life cycle of the coupling and the encoder can be shorten.
- Do not apply tensile strength over 15 N to the cable.

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

E20	0	0	-	8	-	4	-	6	-	6	-	0
Shaft type				6	Conti	rol outp	out					

N: NPN open collector output

V: Voltage output

O Power supply

5:5 VDC== ±5%

Connection

R: Axial cable type

S: Radial cable type

12:12 VDC== ±5%

L: Line driver output

S: Shaft type HB: Hollow Built-in type

O Shaft outer diameter / Shaft inner diameter 2: Ø 2 mm 2.5: Ø 2.5 mm

3: Ø 3 mm B Resolution Number: Refer to resolution in

'Specifications' Output phase

3: A, B, Z $6: A, \overline{A}, B, \overline{B}, Z, \overline{Z}$

Product Components

Shaft type	Shaft type	Hollow Built-in type		
Product Components	Product, Instruction manual			
Bolt	× 4	× 2		
Coupling	×1	-		
Bracket	-	×1		

Connections

- Unused wires must be insulated.
- The metal case and shield cable of encoders must be grounded (F.G.). • F.G. (Frame Ground) must be grounded separately.

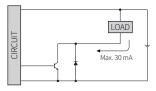
NPN open collector / Line driver output Voltage output

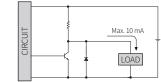
Color	Function	Color	Function	Color	Function	Color	Function
Black	OUTA	Brown	+V	Black	OUTA	Orange	OUT Z
White	OUT B	Blue	GND	Red	OUTĀ	Yellow	OUTZ
Orange	OUT Z	Shield	F.G.	White	OUT B	Brown	+V
				Gray	OUT B	Blue	GND
				Shield	F.G.		

Inner Circuit

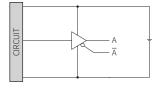
Output circuits are identical for all output phase.

NPN open collector output Voltage output





Line driver output



Output Waveform

- The rotation direction is based on facing the shaft, and it is clockwise (CW) when rotating to the right.
- Phase difference between A and B: $\frac{1}{4} \pm \frac{1}{8}$ (T = 1 cycle of A)

NPN open collector / Line driver output Voltage output <u>1</u>+] Α в z Ē clockwise (CW) 7 7

Specifications

Model	E20	E20					
Resolution	100 / 200 / 320 / 360 PPR model						
Control output	NPN open collector output	Voltage output	Line driver output				
Output phase	A, B, Z	A, B, Z	A, \overline{A} , B, \overline{B} , Z, \overline{Z}				
Inflow current	\leq 30 mA	-	\leq 20 mA				
Residual voltage	\leq 0.4 VDC==	\leq 0.4 VDC==	\leq 0.5 VDC==				
Outflow current	utflow current -		\leq -20 mA				
Output voltage	-	-	\geq 2.5 VDC==				
Response speed ⁰¹⁾	\leq 1 μ s	\leq 0.5 μ s					
Max. response frequency	100 kHz						
Max. allowable revolution ⁰²⁾	6,000 rpm						
Starting torque	\leq 5 \times 10 ⁴ N m						
Inertia moment	$\leq 0.5 \mathrm{g} \cdot \mathrm{cm}^2 (5 \times 10^8 \mathrm{kg} \cdot \mathrm{m}^2)$						
Allowable shaft load	Radial: \leq 200 gf, Thrust: \leq 200 gf						
Unit weight	≈ 35 g						
Approval	C E 毕 E E E E	C€ ‱EME	ERC				

ckwise (CW)

01) Based on cable length: 1 m, I sink: 20 mA

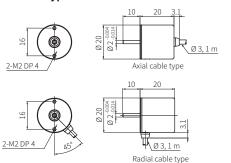
 $\begin{array}{l} \text{(a) Back of collecting in a fin, sink 20 in V \\ \text{(b) Select resolution to satisfy Max. allowable revolution } \\ \text{(max. response revolution (rpm)} = \frac{max. response frequency}{\text{resolution}} \times 60 \text{ sec} \end{array}$

Model	E20	E20				
Power supply	5 VDC== ± 5% (ripple P- 12 VDC== ± 5% (ripple F	5 VDC== ± 5% (ripple P-P: ≤ 5%)				
Current consumption	\leq 60 mA (no load)	\leq 50 mA (no load)				
Insulation resistance	\geq 100 M Ω (500 VDC== m	legger)				
Dielectric strength	Between the charging part and the case: 500 VAC \sim 50 / 60 Hz for 1 minute					
Vibration	1 mm double amplitude for 2 hours	ble amplitude at frequency 10 to 55 Hz in each X, Y, Z direction				
Shock	$\lesssim 50 \text{ G}$					
Ambient temp.	-10 to 70 °C, storage: -20 to 80 °C (no freezing or condensation)					
Ambient humi.	35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation)					
Protection rating	IP50 (IEC standard)					
Connection	Axial / Radial cable type model					
Cable spec.Ø 3 mm, 5-wire (Line driver output: 8-wire), 1 m, shield cable						

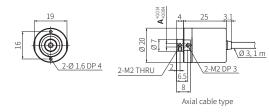
Dimensions

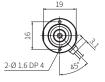
• Unit: mm, For the detailed drawings, follow the Autonics website.

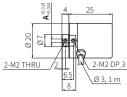
Shaft type



Hollow Built-in type



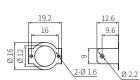


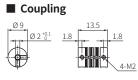


Radial cable type



Bracket





Parallel misalignment: ≤ 0.15 mm
Angular misalignment: ≤ 2°
End-play: ≤ 0.2 mm