Autonics

• Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.

- Δ symbol indicates caution due to special circumstances in which hazards may occur.
- **Warning** Failure to follow instructions may result in serious injury or death.
- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.)
- Failure to follow this instruction may result in personal injury, economic loss or fire.
 20. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire. **03. Install on a device panel to use.**

Failure to follow this instruction may result in fire.

Safety Considerations

- 04. Do not connect, repair, or inspect the unit while connected to a power source.Failure to follow this instruction may result in fire.
- Check 'Connections' before wiring.
 Eailure to follow this instruction may result in fire
- Failure to follow this instruction may result in fire. **06. Do not disassemble or modify the unit.** Failure to follow this instruction may result in fire.

Caution Failure to follow instructions may result in injury or product damage.

- 01. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage. **02. Do not short the load.**
- Failure to follow this instruction may result in fire.
 Oo not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists.
 Failure to follow this instruction may result in product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'.
- Otherwise, It may cause unexpected accidents. • 5 VDC=, 12 - 24 VDC= power supply should be insulated and limited voltage / current or Class 2, SELV power supply device.
- For using the unit with the equipment which generates noise (switching regulator,
 investor accurate the stability of the shield using the back of the stability of the
- inverter, servo motor, etc.), ground the shield wire to the F.G. terminal. • Ground the shield wire to the F.G. terminal.
- When supplying power with SMPS, ground the F.G. terminal and connect the noise canceling capacitor between the 0 V and F.G. terminals.
- Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc. by line resistance or capacity between lines.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications') - Altitude max. 2,000 m
- Altitude max. 2,000 m - Pollution degree 2
- Installation category II

50 mm Diameter Absolute Single-Turn Rotary Encoders (Magnetic)



MGA50 Series PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

Features

- High accuracy in harsh environments including shock, vibration, dust, and humidity (compared to optical encoders)
- Longer service life compared to optical encoders
- Various output code options: BCD, binary, Gray
- Various resolutions: up to 10-bit (1024 divisions)
- Power supply: 5 VDC== ± 5%, 12 24 VDC== ± 5%
- IP50 protection structure (IEC standard)

Cautions during Installation

- Install the unit correctly with the usage environment, location, and the designated specifications.
- Do not load overweight on the shaft.
- Do not put strong impact when insert a coupling into shaft. Failure to follow this instruction may result in product damage
- When fixing the product or coupling with a wrench, tighten under 0.15 N m.
 If the coupling error (parallel misalignment, angular misalignment) between the shaft increases while installation, the life cycle of the coupling and the encoder can be shorten.
- Do not apply tensile strength over 30 N to the cable.

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

O Shaft type S: Shaft type	Rotating direction F: Increase output when the rotating
Shaft outer diameter 8: Ø 8 mm	direction is clockwise base on facing the shaft R: Increase output when the rotating direction is counter-clockwise base or facing the shaft
Resolution Number: Refer to resolution ir Phase / Output Angl	Control output N: NPN open collector output
Output code BCD code Binary code Gray code Gray code	⑦ Power supply 5: 5 VDC== ±5% 24: 12 - 24 VDC== ±5%
Product Component	
	olt \times 7 • Bracket \times 1 pupling \times 1

Connections

- Unused wires must be insulated.
- The metal case and shield cable of encoders must be grounded (F.G.).
- F.G. (Frame Ground) must be grounded separately.
 Since exclusive driver IC is used for output circuit, be aware of short circuits when wiring each output wires. N · C: not connected

BCD code

Color	Function	Refer	
White	+V	Power	
Black	GND		
Brown	2º		
Red	2 ¹		
Orange	2 ²		
Yellow	2 ³		
Green	$2^{0} \times 10$		
Blue	$2^{1} \times 10$		
Purple	$2^{2} \times 10$		
Gray	$2^{3} \times 10$	TP1 $(\leq 64 \text{ division})$	
Pink	$2^{0} \times 10^{2}$	TP2 $(\leq 64 \text{ division})$	
Clear	$2^{1} \times 10^{2}$	EP ($\leq 64 \text{ division}$)	
Light brown	$2^{2} \times 10^{2}$		
Light yellow	$2^{3} \times 10^{2}$		
Light green	$2^{0} \times 10^{3}$		
Light blue	N·C		
Light purple	N·C		
Shield	F.G.	Signal shield	

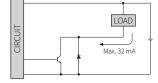
Billary / Oldy couc			
Color	Function	Refer	
White	+V	power	
Black	GND		
Brown	2 ⁰		
Red	2 ¹		
Orange	2 ²		
Yellow	2 ³		
Green	2 ⁴		
Blue	2 ⁵		
Purple	2 ⁶		
Gray	27	TP1 $(\leq 64 \text{ division})$	
Pink	2 ⁸	TP2 $(\leq 64 \text{ division})$	
Clear	2 ⁹	EP (\leq 64 division)	
Light brown	N·C		
Light yellow	N·C		
Light green	N·C		
Light blue	N·C		
Light purple	N·C		
Shield	F.G.	signal shield	

Binary / Grav code

Inner Circuit

• The output circuit is identical for each output bit.

• Be aware of circuit break in case of overload or short beyond the specifications.

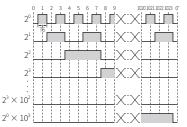


Output Waveform

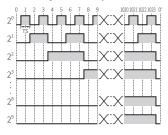
• Following waveform is based on the positive logic.

(In case of negative logic, the waveform is opposite to corresponding waveform.)

BCD code output



Binary code output



Gray code output

2 ⁰			
21	TS		×
22	Щ.	X.	×
2 ³		 J [—] X∷	X
2 ⁸		X	x
29			X

Specifications

Model	MGA50S8	
Resolution 01)	\leq 1024 division	
Output code	BCD / Binary / Gray code model	
Control output	NPN open collector output	
Inflow current	\leq 32 mA	
Residual voltage	≤1VDC==	
Output logic	Negative logic output	
Response speed ⁰²⁾	$\leq 1 \mu s$	
Max. response freq.	30 kHz	
Max. allowable revolution ⁰³⁾	3,000 rpm	
Starting torque	≤ 0.007 N m	
Inertia moment	$\leq 80 \mathrm{g} \cdot \mathrm{cm}^2 (8 \times 10^6 \mathrm{kg} \cdot \mathrm{m}^2)$	
Allowable shaft load	Radial: 10 kgf, Thrust: 2.5 kgf	
Unit weight (packaged)	\approx 270 g (\approx 400 g)	
Approval	C E 监 E ML	
01) Refer to resolution in 'Ou	itput Phase / Output Angle'.	

02) Based on cable length: 2 m, I sink = 32 mA

03) Select resolution to satisfy Max. allowable revolution ≥ Max. response revolution $[max. response revolution (rpm) = \frac{max. response frequency}{resolution} \times 60 \text{ sec}]$

5 VDC== ± 5% (ripple P-P: ≤ 5%) / 12 - 24 VDC== ± 5% (ripple P-P: ≤ 5%) model Power supply **Current consumption** \leq 60 mA (no load) \geq 100 M Ω (500 VDC== megger) Insulation resistance Between the charging part and the case: 750 VAC $\sim 50\,/\,60$ Hz for 1 min. Dielectric strength 1 mm double amplitude at frequency 10 to 55 Hz in each X, Y, Z Vibration direction for 2 hours Shock $\lesssim 75 \, \text{G}$ Ambient temp. -10 to 70 °C, storage: -25 to 85 °C (no freezing or condensation) 35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation) Ambient humi **Protection rating** IP50 (IEC standard) Connection Axial (cable gland) Cable spec. Ø 6 mm, 17-wire, 2 m, shield cable AWG28 (0.08 mm, 17-core), insulator diameter: Ø 0.8 mm Wire spec.

Output Phase / Output Angle

- TP = Timing Pulse
- TS = Signal Pulse
- EP = Even Parity
- Hysterisis = $\pm 0.1^{\circ}$

Positioning error 01 = ± 1 bit (LSB: Least Significant Bit) 01) When power ON / OFF the unit, ± 1 bit (LSB) can be changed at current position due to hysterisis.

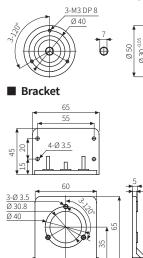
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Resolution	BCD code	Binary code	Gray code
1024	TS: 0.3515° ±15' (13 bit)	TS: 0.3515° ±15' (10 bit)	TS: 0.703° ±15' (10 bit)
720	TS: 0.5° ±25' (11 bit)	TS: 0.5° ±25' (10 bit)	TS: 1° ±25' (10 bit)
512	TS: 0.703° ±25' (11 bit)	TS: 0.703° ±25' (9 bit)	TS: 1.406° ±25' (9 bit)
360	TS: 1° ±25' (10 bit)	TS: 1° ±25' (9 bit)	TS: 2° ±25' (9 bit)
256	TS: 1.406° ±25' (10 bit)	TS: 1.406° ±25' (8 bit)	TS: 2.8125° ±25' (8 bit)
180	TS: 2° ±25' (9 bit)	TS: 2° ±25' (8 bit)	TS: 4° ±25' (8 bit)
128	TS: 2.8125° ±25' (9 bit)	TS: 2.8125° ±25' (7 bit)	TS: 5.625° ±25' (7 bit)
90	TS: 4° ±25' (8 bit)	TS: 4° ±25' (7 bit)	TS: 8° ±25' (7 bit)
64	TP1: 4.5° ±60' (1 bit) TP2: 1.125° ±60' (1 bit) TS: 5.625° ±60' (7 bit) EP: 5.625° ±60' (1 bit)	TP1: 4.5° ±60' (1 bit) TP2: 1.125° ±60' (1 bit) TS: 5.625° ±60' (6 bit) EP: 5.625° ±60' (1 bit)	TP1: 4.5° ±60' (1 bit) TP2: 1.125° ±60' (1 bit) TS: 11.25° ±60' (6 bit) EP: 5.625° ±60' (1 bit)
48	TP1: 6° ±60' (1 bit) TP2: 1.5° ±60' (1 bit) TS: 7.5° ±60' (7 bit) EP: 7.5° ±60' (1 bit)	TP1: $6^{\circ} \pm 60'$ (1 bit) TP2: 1.5° $\pm 60'$ (1 bit) TS: 7.5° $\pm 60'$ (6 bit) EP: 7.5° $\pm 60'$ (1 bit)	TP1: 6° ±60' (1 bit) TP2: 15° ±60' (1 bit) TS: 1.5° ±60' (6 bit) EP: 7.5° ±60' (1 bit)
45	TP1: $6.4^{\circ} \pm 60'$ (1 bit) TP2: $1.6^{\circ} \pm 60'$ (1 bit) TS: $8^{\circ} \pm 60'$ (7 bit) EP: $8^{\circ} \pm 60'$ (1 bit)	TP1: 6.4° ±60' (1 bit) TP2: 1.6° ±60' (1 bit) TS: 8° ±60' (6 bit) EP: 8° ±60' (1 bit)	TP1: 6.4° ±60' (1 bit) TP2: 1.6° ±60' (1 bit) TS: 16° ±60' (6 bit) EP: 8° ±60' (1 bit)
40	TP1: 7.2° ±60' (1 bit) TP2: 1.8° ±60' (1 bit) TS: 9° ±60' (6 bit) EP: 9° ±60' (1 bit)	TP1: 7.2° ±60' (1 bit) TP2: 1.8° ±60' (1 bit) TS: 9° ±60' (6 bit) EP: 9° ±60' (1 bit)	TP1: 7.2° ±60' (1 bit) TP2: 1.8° ±60' (1 bit) TS: 18° ±60' (6 bit) EP: 9° ±60' (1 bit)
32	TP1: 9° ±60' (1 bit) TP2: 2.25° ±60' (1 bit) TS: 11.25° ±60' (6 bit) EP: 11.25° ±60' (1 bit)	TP1: 9° ±60' (1 bit) TP2: 2.25° ±60' (1 bit) TS: 11.25° ±60' (5 bit) EP: 11.25° ±60' (1 bit)	TP1:9° ±60' (1 bit) TP2:2.25° ±60' (1 bit) TS:22.5° ±60' (5 bit) EP:11.25° ±60' (1 bit)

Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.

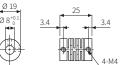
15.8 5

37.5





20



Ø 6, 2 m

Parallel misalignment: ≤ 0.25 mm
Angular misalignment: ≤ 5°
End-play: ≤ 0.5 mm